# **Oriental motor**

## Hollow Shaft Rotary Actuators

**DGII** Series

With horizontally mounted motor Frame Size 85 mm

The **DGII** Series has been extended by actuators with 85 mm frame size where the motor is mounted horizontally.



## Features Flexible Use Depending on Space Requirements

(Example for Standard Type with 85 mm frame size)



## Simplified Installation

- Mounting holes are not required for the motor, so the mounting plate can be simplied.
- An additional mounting pedestal is not required, so mounting is improved.
- Cables and piping can be routed through the legs of the mounting pedestal.



For the new types the gear ratios 12, 18 and 36 are available. This makes the selection regarding speed and torque more flexible.





1	Series Name	DGB: DGII Series
2	Frame Size	<b>85</b> : 85 mm
3	Table Support	R: Cross-Roller Bearing
4	Gear Ratio	
5	Motor Type	AZ: AZ Series
6	Configuration	A: Standard M: With Electromagnetic Brake
0	Motor Specification	C: Single-Phase 200-240 VAC K: 24 VDC/48 VDC
8	Cable Direction	R: Right L: Left

## Product Line

Actuators

#### ♦Standard

Frame Size [mm] Product Name List Price DGB85R12-AZA R DGB85R12-AZA DGB85R18-AZA 85 1,515.00€ DGB85R18-AZA DGB85R36-AZA DGB85R36-AZA\_L

For the power supply input a C (Single-Phase 200-240 VAC) or a K (24 VDC/48 VDC) is indicated where the box  $\square$  is located in the product name.



◇Built-in Controller Type				
Power Supply	Product Name			

Power Supply	Product Name	List Price
Single-Phase 200-240 VAC	AZD-CD	480.00 €
24 VDC/48 VDC	AZD-KD	360.00 €

#### ◇Pulse Input Type

* 1 31			
Power Supply	Product Name	List Price	
Single-Phase 200-240 VAC	AZD-C	430.00 €	
24 VDC/48 VDC	AZD-K	310.00 €	

• For the connection cables please refer to the website www.orientalmotor.eu.

## ♦ With Electromagnetic Brake

•	•		
Frame Size [mm]	Product Name	List Price	
	DGB85R12-AZMCR		
	DGB85R12-AZMCL		
05	DGB85R18-AZMCR	1 0 10 00 0	
85	DGB85R18-AZMCL	1,640.00 €	
	DGB85R36-AZMCR		
	DGB85R36-AZMCL	1	
-		1	





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Power Supply	Product Name	List Price
Single-Phase 200-240 VAC	AZD-CEP	520.00€



## Specifications

#### AC Input

Frame Size		85 mm				
Product Namo	Standard		DGB85R12-AZAC	DGB85R18-AZAC	DGB85R36-AZAC	
FIGULE Name	With Electromagnetic Brake		DGB85R12-AZMC	DGB85R18-AZMC	DGB85R36-AZMC	
	Built-in Controller			AZD-CD		
Driver Product Name	Pulse Input Type with RS-48 Communication	35	AZD-CX			
	Pulse Input Type			AZD-C		
	EtherNet/IP Type			AZD-CEP		
Built-In Motor				AZM46		
Table Support				Cross-Roller Bearing		
Inertia	J	: kg∙m²	11200 × 10 <sup>-7</sup> [13500×10 <sup>-7</sup> ] <b>*</b> 1	21100 × 10 <sup>-7</sup> [26300×10 <sup>-7</sup> ]*1	74500 × 10 <sup>-7</sup> [95300×10 <sup>-7</sup> ] <b>*</b> 1	
Gear Ratio			12	18	36	
Minimum Traveling Amount of the O	utput Table de	g/STEP		0.01		
Permissible Torque		Nm	3	4.5	9	
Holding Torque at Motor Standstill	Power ON	Nm	1.8	2.7	5.4	
Tiolaing forque at motor standstill	Electromagnetic Brake	Nm	1.8	2.7	5.4	
Max. Speed	deg/s	econds	1800 (300 r/min)	1200 (200 r/min)	600 (100 r/min)	
Repetitive Positioning Accuracy	arc	second		±30 (±0.008°) *2		
Backlash	arc	minute		6 (0.1°)		
Angular Transmission Accuracy	arc	minute	6 (0.1°)			
Permissible Axial Load		Ν	500			
Permissible Moment		Nm	10			
Runout of Output Table Surface		mm	0.015			
Runout of Output Table Inner (Outer) Diameter mm		mm	0.015			
Parallelism of Output Table mm		0.030				
Degree of Protection			IP40 (IP20 for motor connector)			
Dower Supply Input	Voltage and Frequency		Single-Phase 200-240 VAC -15~+6% 50/60 Hz			
rower-Supply input	Input Current	А		1.7		
24 VDC±5% *3       Control Power-Supply       0 25 A 10 33 A1*1						

• Either R (right) or L (left) is entered for the cable withdrawing direction in ] in the product name.

\*1 The brackets [ ] indicate the specifications for the electromagnetic brake type.

\*2 For gear ratio 18 the accuracy might be lower when the operating range of the output table exceeds one rotation.

3 Changes to 24 VDC  $\pm$  4% if the electromagnetic brake type has been extended with the 20 m accessory cable.

Note

• The repetitive positioning accuracy is measured at a constant temperature (normal temperature) under a constant load.

It is not possible to disassemble the motor part.

## Speed - Torque Characteristics (Reference Value)



#### Note

Data for the speed – torque characteristics is based on Oriental Motor's internal measurement conditions. If the conditions are changed, the characteristics may also change as a result.
Depending on the driving conditions, a considerable amount of heat may be generated by the motor. Please keep the motor case temperature at a maximum of 80°C to protect the ABZO sensor.
(When conforming to the UL Standards, the temperature of the motor case must be kept at 75°C or less, since the motor is recognized as heat-resistant class A.)

#### $\bigcirc$ Standard Type Frame Size 85 mm

Cable Withdrawing Direction	Product Name	L	Mass [kg]
Cable to the right	DGB85R12-AZACR	100	
Cable to the left	DGB85R12-AZACL	102	
Cable to the right	DGB85R18-AZACR	170	15
Cable to the left	DGB85R18-AZACL	170	1.5
Cable to the right	DGB85R36-AZACR	175	
Cable to the left	DGB85R36-AZACL	175	



Cable to the right	Cable to the left	

• The \_\_\_\_\_ shaded areas are rotating parts. \*The home sensor set cannot be used.

 $\bigcirc$  With Electromagnetic Brake Frame Size 85 mm

Cable Withdrawing Direction	Product Name	L	Mass [kg]
Cable to the right	DGB85R12-AZMCR	213	1.7
Cable to the left	DGB85R12-AZMCL		
Cable to the right	DGB85R18-AZMCR	200	
Cable to the left	DGB85R18-AZMCL	209	
Cable to the right	DGB85R36-AZMCR		
Cable to the left	DGB85R36-AZMCL	200	





• The \_\_\_\_\_ shaded areas are rotating parts.

 $\ensuremath{\boldsymbol{\ast}}\xspace$  The home sensor set cannot be used.

## Specifications

#### DC Input

Fran	ne Size	85 mm			
Product Name	Single Shaft	DGB85R12-AZAK	DGB85R18-AZAK	DGB85R36-AZAK	
	Built-in Controller Type	AZD-KD AZD-KX			
Driver Product Name	Pulse Input Type with RS-485 Communication				
	Pulse Input Type	AZD-K			
Built-In Motor			AZM46		
Table Support			Cross-Roller Bearing		
Inertia	J: kg⋅m²	$11200 \times 10^{-7}$	21100 × 10 <sup>-7</sup>	74500 × 10 <sup>-7</sup>	
Gear Ratio		12	18	36	
Minimum Traveling Amount of the (	Dutput Table deg/STEP		0.01		
Permissible Torque Nm		3	4.5	9	
Holding Torque at Motor Standstill	Nm	1.8	2.7	5.4	
Max. Speed	deg/seconds	1800 (300 r/min)	1200 (200 r/min)	600 (100 r/min)	
Repetitive Positioning Accuracy	arc second		±30 (±0.008°) <b>*</b> 2		
Backlash	arc minute		6 (0.1°)		
Angular Transmission Accuracy	arc minute		6 (0.1°)		
Permissible Axial Load	Ν		500		
Permissible Moment	Nm		10		
Runout of Output Table Surface	mm	0.015			
Runout of Output Table Inner (Outer) Diameter mm		0.015			
Parallelism of Output Table mm			0.030		
Degree of Protection		IP40 (IP20 for motor connector)			
Power-Supply Input	Voltage		$24 \text{ VDC} \pm 5\% \overline{/48} \text{ VDC} \pm 5\%$		
rower-supply input	Input Current A	1.72			

• Either **R** (right) or **L** (left) is entered for the cable withdrawing direction in  $\Box$  in the product name.

• The repetitive positioning accuracy is measured at a constant temperature (normal temperature) under a constant load.

It is not possible to disassemble the motor part.

\*1 Only for the Actuator.

\$2 For gear ratio 18 the accuracy might be lower when the operating range of the output table exceeds one rotation.

## Speed - Torque Characteristics (Reference Value)



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#### DGB85R36



**91**\*\*1CE

### Note

Data for the speed – torque characteristics is based on Oriental Motor's internal measurement conditions. If the conditions are changed, the characteristics may also change as a result.
Depending on the driving conditions, a considerable amount of heat may be generated by the motor. Please keep the motor case temperature at a maximum of 80°C to protect the ABZO sensor.
(When conforming to the UL Standards, the temperature of the motor case must be kept at 75°C or less, since the motor is recognized as heat-resistant class A.)

#### ♦ Standard Type Frame Size 85 mm

Cable Withdrawing Direction	Product Name	L	Mass [kg]	
Cable to the right	DGB85R12-AZAKR	100		
Cable to the left	DGB85R12-AZAKL	102	1.5	
Cable to the right	DGB85R18-AZAKR	170		
Cable to the left	DGB85R18-AZAKL	170	1.5	
Cable to the right	DGB85R36-AZAKR	175	-	
Cable to the left	DGB85R36-AZAKL	175		



Cable to the right	Cable to the left

• The \_\_\_\_\_ shaded areas are rotating parts.

 $\ensuremath{\boldsymbol{\ast}}\xspace$  The home sensor set cannot be used.



# **AZ** Multi-Axis-Driver

## DC Power supply Supports EtherCAT Drive Profiles

The multi-axis driver corresponds to the EtherCAT communication drive profile CiA402. Two, three or four **AZ** motors with DC power supply, as well as actuators equipped with them, can be connected. This includes the new **DGB85** types.

## Types

Product Name	Number of axes	List Price
AZD2A-KED	2	733.00 €
AZD3A-KED	3	971.00€
AZD4A-KED	4	1,173.00 €

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